

# FEB154-001 User's Guide Motor Control Evaluation Board Using the Motion-SPM™ (FSBB20CH60) in a Mini-DIP (44mm x 26.8mm) Package





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#### 1. Introduction

This user's guide supports the FSBB20CH60 Motion-SPM<sup>™</sup> in a mini-DIP package evaluation board. It should be used in conjunction with the FSBB20CH60 data sheet and Fairchild's SPM application note AN-9035.

#### **1.1 Product Description**

Fairchild's Smart power Module (SPM<sup>TM</sup>) products provide efficient motor control for energyrestricted low-power inverter-driven applications, such as washing machines and air conditioners. The FSBB20CH60 Motion-SPM<sup>TM</sup> integrates three high-voltage ICs (HVICs), one low-voltage IC (LVIC), six IGBTs for three-phase inverter and six fast recovery diodes. Fairchild's Motion-SPM reduces board space by utilizing an ultra-compact 44mm x 26.8mm Mini-DIP package and by incorporating built-in HVICs that provide an optocoupler-less, single supply IGBT gate driving capability. The FSBB20CH60 product offers designers high reliability with integrated under-voltage lock out (UVLO) and short circuit (SC) protection.

#### **1.2 Circuit Description**

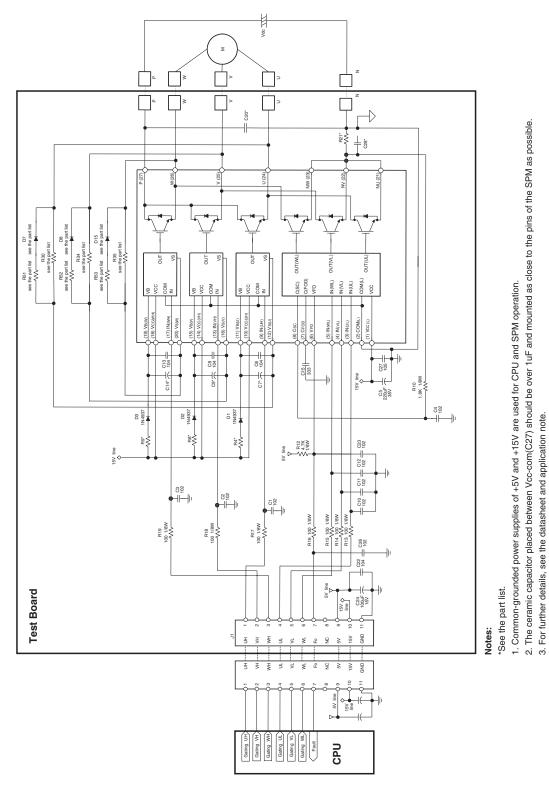
The Motion-SPM is installed as the switching module in this evaluation board and has direct interface with the CPU using one shunt resistor. The DC-link(P and N) input terminals are connected into the corresponding terminals in Motion-SPM and three-phase (U,V,W) output terminals from SPM are wired into motor input. Since the three HVICs are integrated in the Motion-SPM, 3 parts of bootstrap circuit are needed, which consists of bootstrap capacitor, charge resistor for charging boost capacitor, blocking diode for high voltage isolation. One shunt resistor is used for sensing short current and the related short current circuit is composed of an external shunt resistor and R-C low pass filter. The signal of fault output pin VFO drops from high level to low when a fault, such as UV (Under Voltage) or SC (Short Circuit), happens. A pull-up resistor and filter capacitor are needed to support this action. Six R-C low pass filters are used between input connector from a DSP controller (or other controllers) and gate input signal pins of Motion-SPM.



## 2.1 Schematic

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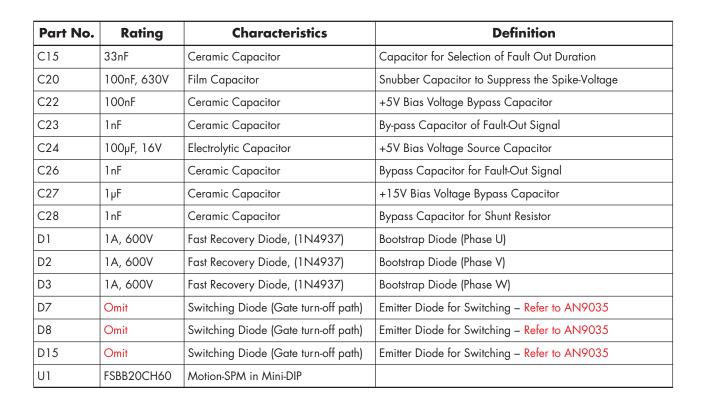
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# 2.2 Bill of Materials

Part No.	Rating	Characteristics	Definition
R4	20W, 1/4W	Carbon Film Resistor (5%)	Bootstrap Resistor (Phase U)
R8	20W, 1/4W	Carbon Film Resistor (5%)	Bootstrap Resistor (Phase V)
R9	20W, 1/4W	Carbon Film Resistor (5%)	Bootstrap Resistor (Phase W)
R10	1.8kW, 1/8W	Carbon Film Resistor (5%)	Low-Pass-Filter for Current Sensing
R12	4.7kW, 1/8W	Carbon Film Resistor (5%)	Pull-Up Resistor (Fault-Out)
R13	100W, 1/8W	Carbon Film Resistor (5%)	Series Resistor for Signal Interface (UL)
R14	100W, 1/8W	Carbon Film Resistor (5%)	Series Resistor for Signal Interface (VL)
R15	100W, 1/8W	Carbon Film Resistor (5%)	Series Resistor for Signal Interface (WL)
R16	100W, 1/8W	Carbon Film Resistor (5%)	Series Resistor for Signal Interface (Fault-Out)
R17	100W, 1/8W	Carbon Film Resistor (5%)	Series Resistor for Signal Interface (UH)
R18	100W, 1/8W	Carbon Film Resistor (5%)	Series Resistor for Signal Interface (VH)
R19	100W, 1/8W	Carbon Film Resistor (5%)	Series Resistor for Signal Interface (WH)
R21	15mW , 5W	Non-inductive Resistor (1%)	Shunt Resistor for Current Sensing (OC Level: about 33A)
R30	5.6W, 1/4W	Carbon Film Resistor (5%)	Emitter Resistor for Switching
R34	5.6W, 1/4W	Carbon Film Resistor (5%)	Emitter Resistor for Switching
R35	5.6W, 1/4W	Carbon Film Resistor (5%)	Emitter Resistor for Switching
R51	Omit	Carbon Film Resistor (5%)	Emitter Resistor for Switching – Refer to AN9035
R52	Omit	Carbon Film Resistor (5%)	Emitter Resistor for Switching – Refer to AN9035
R53	Omit	Carbon Film Resistor (5%)	Emitter Resistor for Switching – Refer to AN9035
C1	lnF	Ceramic Capacitor	High-Side Pull-down Capacitor (Phase U)
C2	lnF	Ceramic Capacitor	High-Side Pull-down Capacitor (Phase V)
C3	lnF	Ceramic Capacitor	High-Side Pull-down Capacitor (Phase W)
C4	lnF	Ceramic Capacitor	Bypass Capacitor for Current Sensing
C5	220µF, 35V	Electrolytic Capacitor	+15V Bias Voltage Source Capacitor
C6	100nF	Ceramic Capacitor	Bypass Capacitor for Bootstrap Supply (Phase U)
C7	6.8uF, 35V	Electrolytic Capacitor	Bootstrap Capacitor (Phase U)
C8	100nF	Ceramic Capacitor	Bypass Capacitor for Bootstrap Supply (Phase V)
С9	6.8uF, 35V	Electrolytic Capacitor	Bootstrap Capacitor (Phase V)
C10	lnF	Ceramic Capacitor	Low-Side Pull-down Capacitor (Phase U)
C11	lnF	Ceramic Capacitor	Low-Side Pull- down Capacitor (Phase V)
C12	lnF	Ceramic Capacitor	Low-Side Pull- down Capacitor (Phase W)
C13	100nF	Ceramic Capacitor	Bypass Capacitor for Bootstrap Supply (Phase W)
C14	6.8µF, 35V	Electrolytic Capacitor	Bootstrap Capacitor (Phase W)



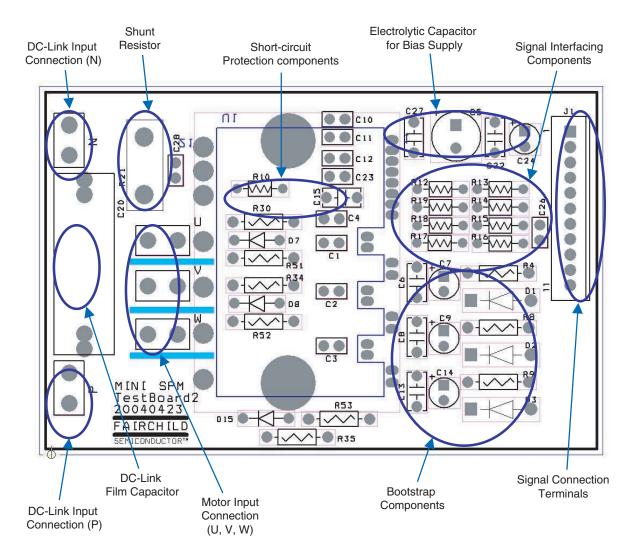
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# 2.3 Printed Circuit Board

## 2.3.1 PCB Map



### 2.3.2 Circuit Layout Design

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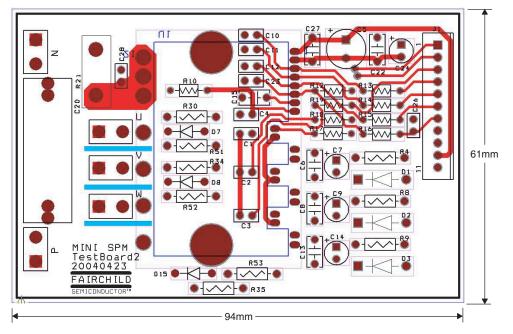
- 1. To avoid malfunction, the wiring of each input should be as short as possible. (less than 2–3cm)
- 2. To prevent protection function errors, the 'R10' and 'Csc' wiring should be as short as possible.
- 3. All the by-pass capacitors and filter capacitors should be placed very close to SPM.
- 4. The short-circuit protection time constant R10 CSC should be set in the range of 1~2µsec.
- 5. The isolation distance of DC-P, U-phase, V-phase, W-phase, DC-N/GND blocks should be over 2.54mm(100mil) for 300V-500V P-N voltage.
- 6. Power-GND and signal-GND should be connected with each other through only one 1.5~2mm width pattern.
- 7. To prevent surge destruction, the wiring between the filter capacitor and the P & Ground pins should be as short as possible. The use of a high frequency non-inductive capacitor of around  $0.1-0.22\mu$ F between the P & Ground pins is recommended. In addition to reducing local voltage spikes, the placement and quality of this capacitor will have a direct impact on both conducted and radiated EMI.

	1	
Signal Interface (J1)		High-Side Input Signal from CPU (Phase U)
	2	High-Side Input Signal from CPU (Phase V)
	3	High-Side Input Signal from CPU (Phase W)
	4	Low-Side Input Signal from CPU (Phase U)
	5	Low-Side Input Signal from CPU (Phase V)
	6	Low-Side Input Signal from CPU (Phase W)
	7	Fault-Out Signal to CPU
	8	NC
	9	SPM Bias Supply +5V Terminal
	10	SPM Bias Supply +15V Terminal
	11	SPM Bias Supply Ground Terminal
Power Connection	Р	Positive DC Link Input Connection
	N	Negative DC Link Input Connection
	U	Motor Input Connection (Phase U)
	V	Motor Input Connection (Phase V)
	W	Motor Input Connection (Phase W)

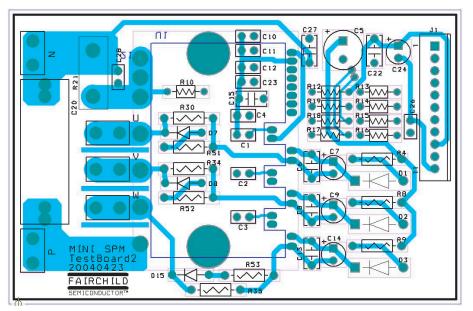
## 2.3.3 External Connection



# 2.3.4 Wiring of PCB



(a) Top Side View



(b) Bottom Side View

#### WARNING AND DISCLAIMER

Replace components on the Evaluation Board only with those parts shown on the parts list in the User's Guide. Contact an authorized Fairchild representative with any questions.

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	DOME™	GTO™່	MicroPak™	QFET <sup>®</sup>	SuperSOT™-8
	EcoSPARK™	HiSeC™	MICROWIRE™	QS™	SyncFET™
	E <sup>2</sup> CMOS™	l²C™	MSX™	QT Optoelectronics™	TinyLogic <sup>®</sup>
	EnSigna™	<i>i-L</i> o™	MSXPro™	Quiet Series <sup>™</sup>	TINYOPTO™
	FACT™	ImpliedDisconnect <sup>™</sup>	OCX™	RapidConfigure™	TruTranslation™
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